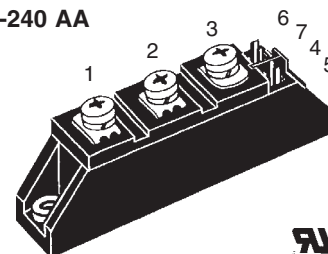
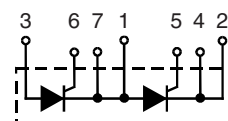
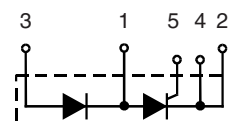
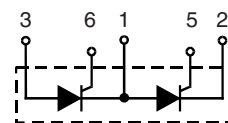
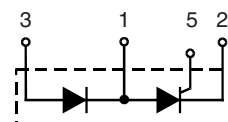


# Thyristor Modules

## Thyristor/Diode Modules

$I_{TRMS} = 2 \times 50 \text{ A}$   
 $I_{TAVM} = 2 \times 32 \text{ A}$   
 $V_{RRM} = 800-1600 \text{ V}$

$V_{RSM}$	$V_{RRM}$	Type					
$V_{DSM}$	$V_{DRM}$	Version			Version		
V	V	1 B	8 B	1 B	8 B	1 B	8 B
900	800	MCC 26-08	io1 B / io8 B	MCD 26-08	io1 B / io8 B		
1300	1200	MCC 26-12	io1 B / io8 B	MCD 26-12	io1 B / io8 B		
1500	1400	MCC 26-14	io1 B / io8 B	MCD 26-14	io1 B / io8 B		
1700	1600	MCC 26-16	io1 B / io8 B	MCD 26-16	io1 B / io8 B		

**TO-240 AA**

**MCC**  
**Version 1 B**

**MCD**  
**Version 1 B**

**MCC**  
**Version 8 B**

**MCD**  
**Version 8 B**


Symbol	Conditions	Maximum Ratings	
$I_{TRMS}, I_{FRMS}$	$T_{VJ} = T_{VJM}$	50	A
$I_{TAVM}, I_{FAVM}$	$T_C = 75^\circ\text{C}; 180^\circ \text{ sine}$	32	A
	$T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$	27	A
$I_{TSM}, I_{FSM}$	$T_{VJ} = 45^\circ\text{C};$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	520 A 560 A
	$T_{VJ} = T_{VJM}$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	460 A 500 A
$\int i^2 dt$	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	1350 A <sup>2</sup> s 1300 A <sup>2</sup> s
	$T_{VJ} = T_{VJM}$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	1050 A <sup>2</sup> s 1030 A <sup>2</sup> s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$	repetitive, $I_T = 45 \text{ A}$	150 A/ $\mu\text{s}$
		non repetitive, $I_T = I_{TAVM}$	500 A/ $\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM};$ $R_{GK} = \infty; \text{ method 1 (linear voltage rise)}$	$V_{DR} = \frac{2}{3} V_{DRM}$	1000 V/ $\mu\text{s}$
$P_{GM}$	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$	$t_p = 30 \mu\text{s}$ $t_p = 300 \mu\text{s}$	10 W 5 W
$P_{GAV}$			0.5 W
$V_{RGM}$			10 V
$T_{VJ}$			-40...+125 °C
$T_{VJM}$			125 °C
$T_{stg}$			-40...+125 °C
$V_{ISOL}$	50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ min}$ $t = 1 \text{ s}$	3000 V~ 3600 V~
$M_d$	Mounting torque (M5) Terminal connection torque (M5)		2.5-4.0/22-35 Nm/lb.in. 2.5-4.0/22-35 Nm/lb.in.
<b>Weight</b>	Typical including screws		90 g

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.

### Features

- International standard package, JEDEC TO-240 AA
- Direct copper bonded  $\text{Al}_2\text{O}_3$  -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1B

### Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

### Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

Symbol	Conditions	Characteristic Values
$I_{RRM}, I_{DRM}$	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	3 mA
$V_T, V_F$	$I_T, I_F = 80 \text{ A}; T_{VJ} = 25^\circ\text{C}$	1.64 V
$V_{T0}$	For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )	0.85 V
$r_T$		11.0 mΩ
$V_{GT}$	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	1.5 V
	$T_{VJ} = -40^\circ\text{C}$	1.6 V
$I_{GT}$	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	100 mA
	$T_{VJ} = -40^\circ\text{C}$	200 mA
$V_{GD}$	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	0.2 V
$I_{GD}$		10 mA
$I_L$	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}; V_D = 6 \text{ V}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	450 mA
$I_H$	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	200 mA
$t_{gd}$	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	2 μs
$t_q$	$T_{VJ} = T_{VJM}; I_T = 20 \text{ A}, t_p = 200 \mu\text{s}; -di/dt = 10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}; dv/dt = 20 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	typ. 150 μs
$Q_S$	$T_{VJ} = T_{VJM}; I_T, I_F = 25 \text{ A}, -di/dt = 0.64 \text{ A}/\mu\text{s}$	50 μC
$I_{RM}$		6 A
$R_{thJC}$	per thyristor/diode; DC current per module	0.88 K/W
$R_{thJK}$	per thyristor/diode; DC current per module	0.44 K/W 1.08 K/W 0.54 K/W
	other values see Fig. 8/9	
$d_S$	Creepage distance on surface	12.7 mm
$d_A$	Strike distance through air	9.6 mm
$a$	Maximum allowable acceleration	50 m/s <sup>2</sup>

Optional accessories for module-type MCC 26 version 1 B

Keyed gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red

Type **ZY 200L** (L = Left for pin pair 4/5) UL 758, style 1385,  
Type **ZY 200R** (R = right for pin pair 6/7) CSA class 5851, guide 460-1-1

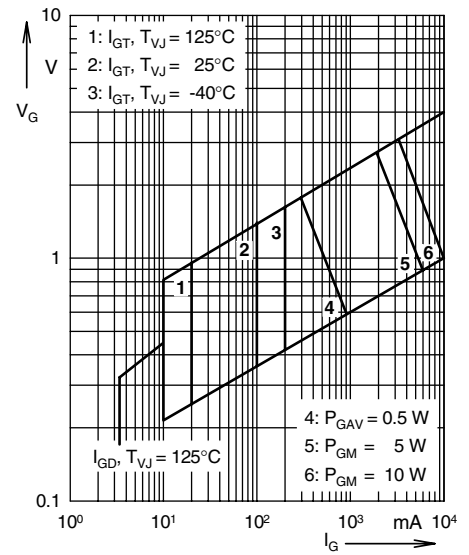


Fig. 1 Gate trigger characteristics

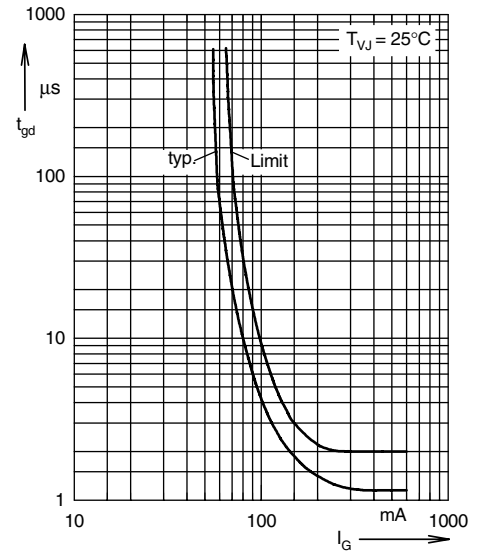
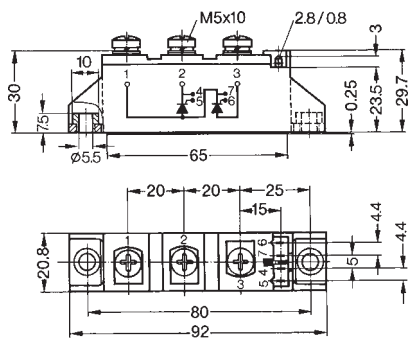


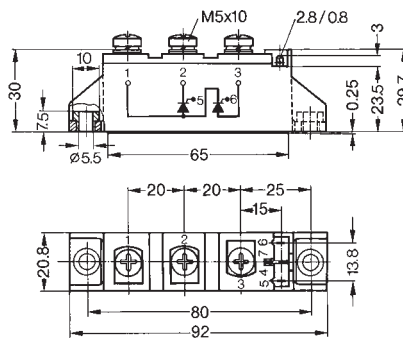
Fig. 2 Gate trigger delay time

Dimensions in mm (1 mm = 0.0394")

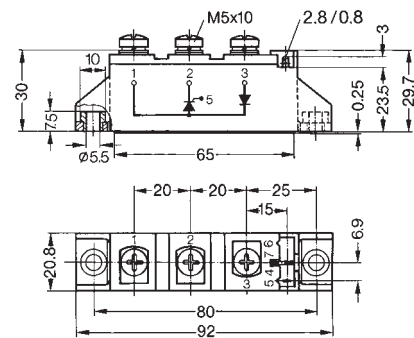
### MCC Version 1 B



### MCC Version 8 B



### MCD Version 8 B



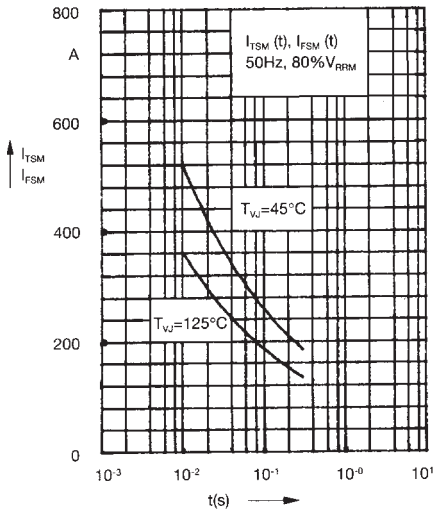


Fig. 3 Surge overload current  
 $I_{TSM}$ ,  $I_{FSM}$ : Crest value, t: duration

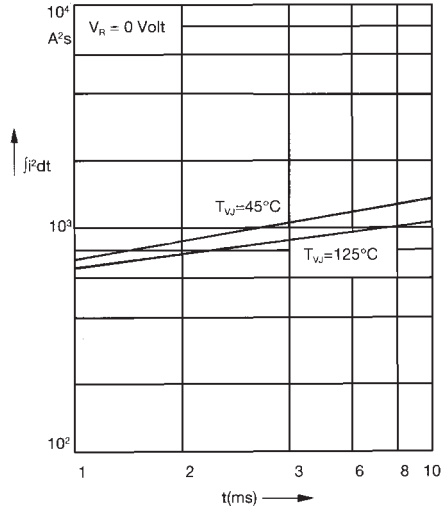


Fig. 4  $j^2t$  versus time (1-10 ms)

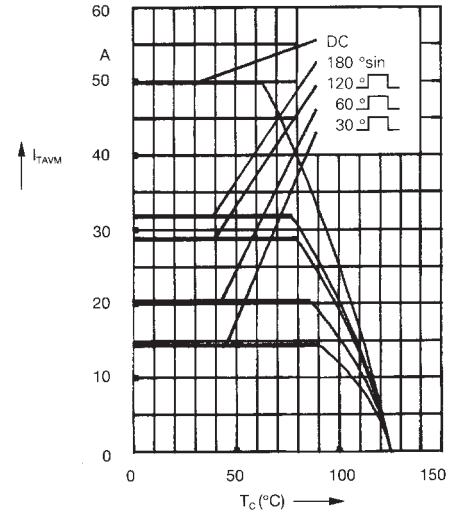


Fig. 4a Maximum forward current at case temperature

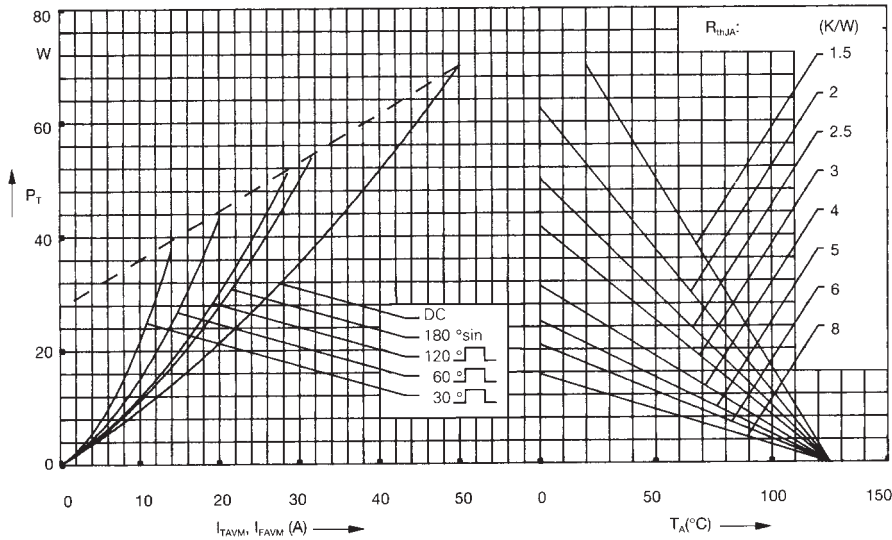


Fig. 5 Power dissipation versus on-state current and ambient temperature (per thyristor or diode)

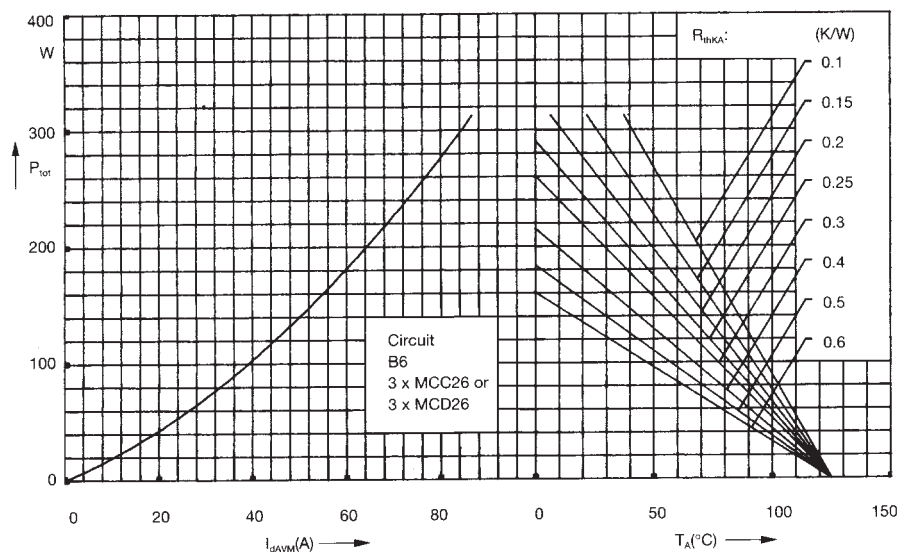


Fig. 6 Three phase rectifier bridge: Power dissipation versus direct output current and ambient temperature

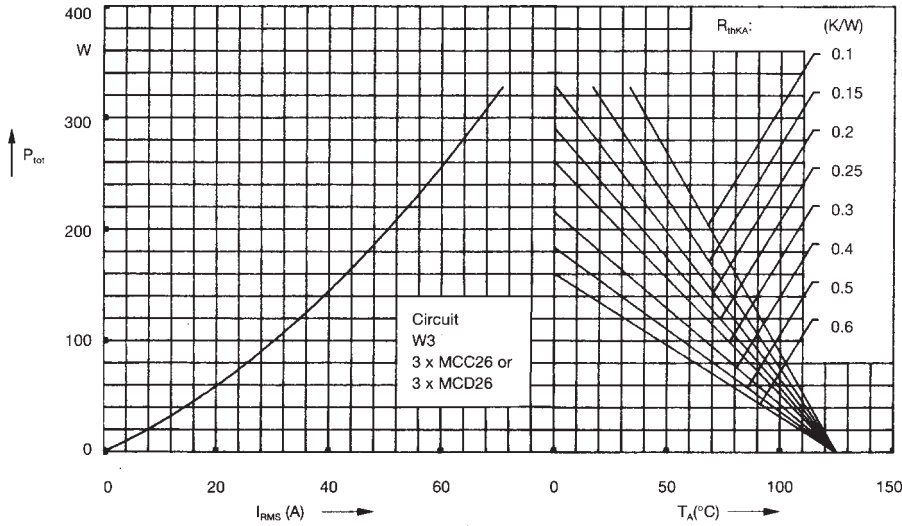


Fig. 7 Three phase AC-controller: Power dissipation versus RMS output current and ambient temperature

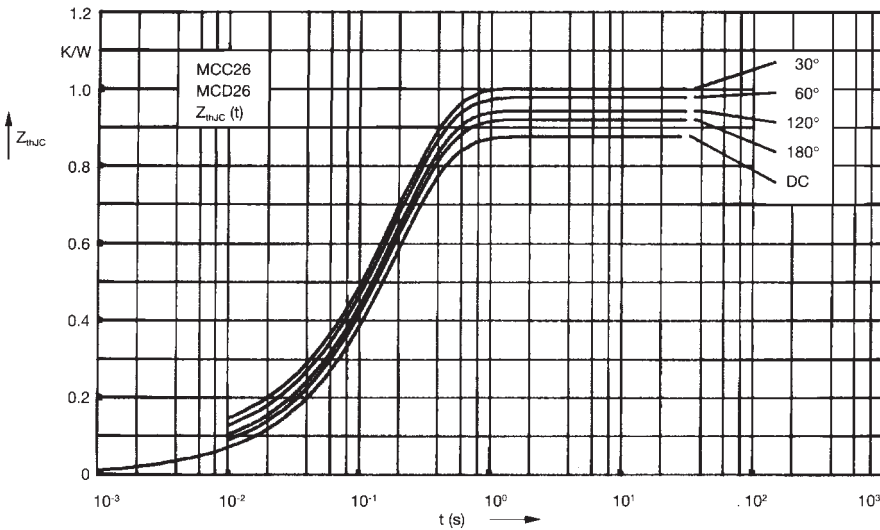


Fig. 8 Transient thermal impedance junction to case (per thyristor or diode)

$R_{thjC}$  for various conduction angles  $d$ :

$d$	$R_{thjC}$ (K/W)
DC	0.88
180°	0.92
120°	0.95
60°	0.98
30°	1.01

Constants for  $Z_{thjC}$  calculation:

$i$	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.019	0.0031
2	0.029	0.0216
3	0.832	0.191

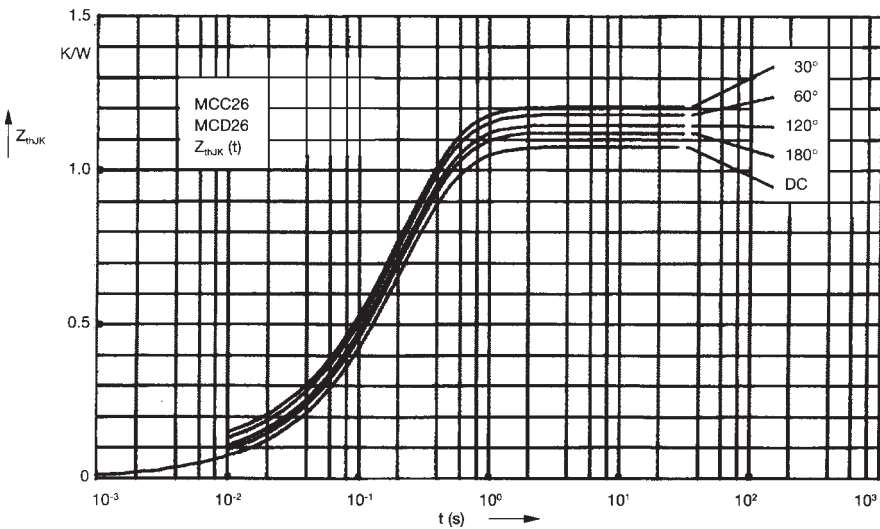


Fig. 9 Transient thermal impedance junction to heatsink (per thyristor or diode)

$R_{thjK}$  for various conduction angles  $d$ :

$d$	$R_{thjK}$ (K/W)
DC	1.08
180°	1.12
120°	1.15
60°	1.18
30°	1.21

Constants for  $Z_{thjK}$  calculation:

$i$	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.019	0.0031
2	0.029	0.0216
3	0.832	0.191
4	0.2	0.45