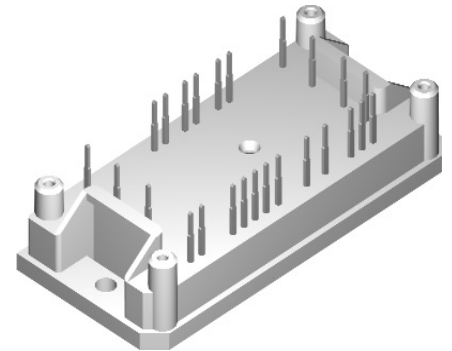
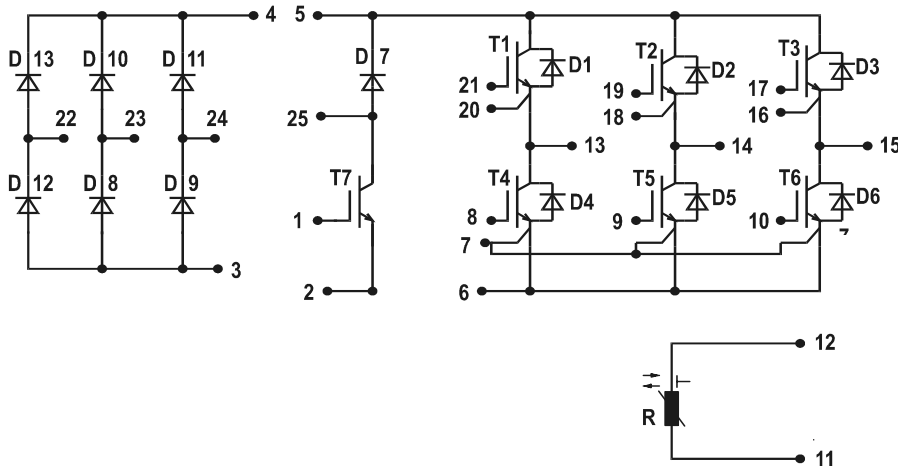


Converter - Brake - Inverter Module (CBI1)

NPT IGBT



| Three Phase Rectifier | Brake Chopper | Three Phase Inverter |
|-----------------------|-----------------------|-----------------------|
| $V_{RRM} = 1600V$ | $V_{CES} = 1200 V$ | $V_{CES} = 1200 V$ |
| $I_{DAVM25} = 130 A$ | $I_{C25} = 19 A$ | $I_{C25} = 19 A$ |
| $I_{FSM} = 300 A$ | $V_{CE(sat)} = 2.9 V$ | $V_{CE(sat)} = 2.9 V$ |

Input Rectifier Bridge D8 - D13

| Symbol | Conditions | Maximum Ratings | |
|------------|--|-----------------|---|
| V_{RRM} | | 1600 | V |
| I_{FAV} | $T_C = 80^\circ C$; sine 180° | 31 | A |
| I_{DAVM} | bridge output current; $T_C = 80^\circ C$; rectangular; $d = 1/3$ | 89 | A |
| I_{FSM} | $T_{VJ} = 25^\circ C$; $t = 10$ ms; sine 50 Hz | 320 | A |
| P_{tot} | $T_C = 25^\circ C$ | 80 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^\circ C$, unless otherwise specified) | | |
|--------------------------|---|--|------------|-------------------|
| | | min. | typ. | max. |
| V_F | $I_F = 30 A$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 1.0 1.1 | 1.35 V V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 0.4 | 0.02 mA mA |
| R_{thJC} R_{thCH} | (per diode) | | 0.45 | 1.4 K/W K/W |

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- Inverter with NPT IGBTs
 - low saturation voltage
 - positive temperature coefficient
 - fast switching
 - short tail current
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Output Inverter T1 - T6

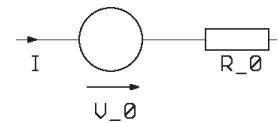
| Symbol | Conditions | Maximum Ratings | |
|--|--|---|---------------|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| V_{GES} | Continuous | ± 20 | V |
| V_{GEM} | Transient | ± 30 | V |
| I_{C25} | $T_C = 25^{\circ}\text{C}$ | 19 | A |
| I_{C80} | $T_C = 80^{\circ}\text{C}$ | 13 | A |
| RBSOA | $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$ | $I_{CM} = 26$ $V_{CEK} \leq V_{CES}$ | A |
| t_{SC} (SCSOA) | $V_{CE} = 720\text{ V}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive | 10 | μs |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 90 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | |
|--|--|--|-----------------------|----------------------|
| | | min. | typ. | max. |
| $V_{CE(sat)}$ | $I_C = 15\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 3.0 3.5 | V V |
| $V_{GE(th)}$ | $I_C = 0.35\text{ mA}$; $V_{GE} = V_{CE}$ | 4.5 | | 6.5 V |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 1.3 | 0.6 mA mA |
| I_{GES} | $V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$ | | | 100 nA |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off} | Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600\text{ V}$; $I_C = 10\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$ | | 50 40 290 60 | ns ns ns ns |
| | | | 1.2 | mJ |
| | | | 1.1 | mJ |
| C_{ies} | | $V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$ | 600 | pF |
| Q_{Gon} | | $V_{CE} = 600\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 10\text{ A}$ | 45 | nC |
| R_{thJC} R_{thCH} | | (per IGBT) | 0.5 | 1.35 KW KW |

Output Inverter D1 - D6

| Symbol | Conditions | Maximum Ratings | |
|-----------|----------------------------|-----------------|---|
| I_{F25} | $T_C = 25^{\circ}\text{C}$ | 26 | A |
| I_{F80} | $T_C = 80^{\circ}\text{C}$ | 17 | A |

| Symbol | Conditions | Characteristic Values | | |
|--------------------------|--|-----------------------|-----------------|------------|
| | | min. | typ. | max. |
| V_F | $I_F = 30\text{ A}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 2.3 | 3.4 V V |
| I_{RM} t_{rr} | $I_F = 15\text{ A}$; $di_F/dt = -400\text{ A}/\mu\text{s}$; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600\text{ V}$; $V_{GE} = 0\text{ V}$ | | 16 | A |
| | | | 130 | ns |
| R_{thJC} R_{thCH} | (per diode) | 0.55 | 1.6 KW KW | |

Equivalent Circuits for Simulation
Conduction

D8 - D13

Rectifier Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_0 = 0.90\text{ V}$; $R_0 = 9\text{ m}\Omega$

T1 - T6 / D1 - D6

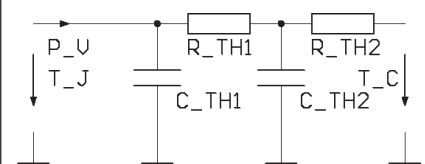
IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^{\circ}\text{C}$)
 $V_0 = 1.50\text{ V}$; $R_0 = 120\text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_0 = 1.46\text{ V}$; $R_0 = 31\text{ m}\Omega$

T7 / D7

IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^{\circ}\text{C}$)
 $V_0 = 1.50\text{ V}$; $R_0 = 120\text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_0 = 1.46\text{ V}$; $R_0 = 63\text{ m}\Omega$

Thermal Response

D8 - D13

Rectifier Diode (typ.)
 $C_{th1} = tbd\text{ J/K}$; $R_{th1} = tbd\text{ K/W}$
 $C_{th2} = tbd\text{ J/K}$; $R_{th2} = tbd\text{ K/W}$

T1 - T6 / D1 - D6

IGBT (typ.)
 $C_{th1} = tbd\text{ J/K}$; $R_{th1} = tbd\text{ K/W}$
 $C_{th2} = tbd\text{ J/K}$; $R_{th2} = tbd\text{ K/W}$

Free Wheeling Diode (typ.)
 $C_{th1} = tbd\text{ J/K}$; $R_{th1} = tbd\text{ K/W}$
 $C_{th2} = tbd\text{ J/K}$; $R_{th2} = tbd\text{ K/W}$

T7 / D7

IGBT (typ.)
 $C_{th1} = tbd\text{ J/K}$; $R_{th1} = tbd\text{ K/W}$
 $C_{th2} = tbd\text{ J/K}$; $R_{th2} = tbd\text{ K/W}$

Free Wheeling Diode (typ.)
 $C_{th1} = tbd\text{ J/K}$; $R_{th1} = tbd\text{ K/W}$
 $C_{th2} = tbd\text{ J/K}$; $R_{th2} = tbd\text{ K/W}$

Brake Chopper T7

| Symbol | Conditions | Maximum Ratings | |
|----------------------------|--|---|---------------|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| V_{GES} | Continuous | ± 20 | V |
| V_{GEM} | Transient | ± 30 | V |
| I_{C25} | $T_C = 25^{\circ}\text{C}$ | 19 | A |
| I_{C80} | $T_C = 80^{\circ}\text{C}$ | 13 | A |
| RBSOA | $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$ | $I_{CM} = 20$ $V_{CEK} \leq V_{CES}$ | A |
| t_{SC} (SCSOA) | $V_{CE} = 720\text{ V}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive | 10 | μs |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 90 | W |

| Symbol | Conditions ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | Characteristic Values | | | |
|--|--|--|-------------------------------------|----------------------------------|-----------------|
| | | min. | typ. | max. | |
| $V_{CE(sat)}$ | $I_C = 15\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 2.9 3.5 | V V | |
| $V_{GE(th)}$ | $I_C = 0.4\text{ mA}$; $V_{GE} = V_{CE}$ | 4.5 | | 6.5 V | |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 0.8 | 0.5 mA mA | |
| I_{GES} | $V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$ | | | 100 nA | |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off} | Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600\text{ V}$; $I_C = 10\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 82\ \Omega$ | | 45 40 290 60 1.2 1.1 | ns ns ns ns mJ mJ | |
| C_{ies} | | $V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$ | 600 | | pF |
| Q_{Gon} | | $V_{CE} = 600\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 10\text{ A}$ | 45 | | nC |
| R_{thJC} R_{thCH} | | | 0.45 | | 1.37 K/W K/W |

Brake Chopper D7

| Symbol | Conditions | Maximum Ratings | |
|-----------|--|-----------------|---|
| V_{RRM} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| I_{F25} | $T_C = 25^{\circ}\text{C}$ | 15 | A |
| I_{F80} | $T_C = 80^{\circ}\text{C}$ | 10 | A |

| Symbol | Conditions | Characteristic Values | | |
|--------------------------|--|-----------------------|-----------|---------------|
| | | min. | typ. | max. |
| V_F | $I_F = 15\text{ A}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 2.0 | 3.5 V V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 0.2 | 0.06 mA mA |
| I_{RM} t_{rr} | } $I_F = 10\text{ A}$; $di_F/dt = -400\text{ A}/\mu\text{s}$; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600\text{ V}$ | | 13 110 | A ns |
| R_{thJC} R_{thCH} | | | 0.85 | |

Temperature Sensor NTC

| Symbol | Conditions | Characteristic Values | | |
|-------------|--------------------------|-----------------------|------|----------------|
| | | min. | typ. | max. |
| R_{25} | $T = 25^{\circ}\text{C}$ | 4.45 | 4.7 | 5.0 k Ω |
| $B_{25/85}$ | | | 3510 | K |

Module

| Symbol | Conditions | Maximum Ratings | |
|------------|--|-----------------|--------------------|
| T_{VJ} | Operating | -40...+125 | $^{\circ}\text{C}$ |
| T_{JM} | | 150 | $^{\circ}\text{C}$ |
| T_{stg} | | -40...+125 | $^{\circ}\text{C}$ |
| V_{ISOL} | $I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$ | 2500 | V~ |
| M_d | Mounting torque (M4) | 2.0 - 2.2 | Nm |

| Symbol | Conditions | Characteristic Values | | |
|---------------|---|-----------------------|------|------|
| | | min. | typ. | max. |
| d_s | Creepage distance (towards heatsink) | 12.7 | | mm |
| d_A | Strike distance in air (towards heatsink) | 12.7 | | mm |
| Weight | | 40 | | g |

