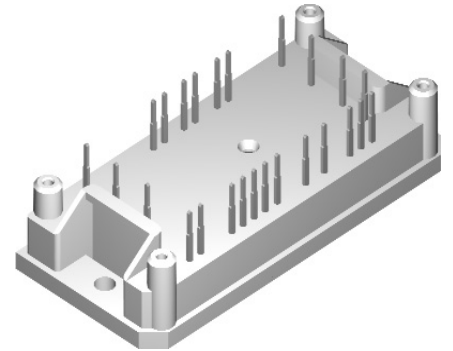
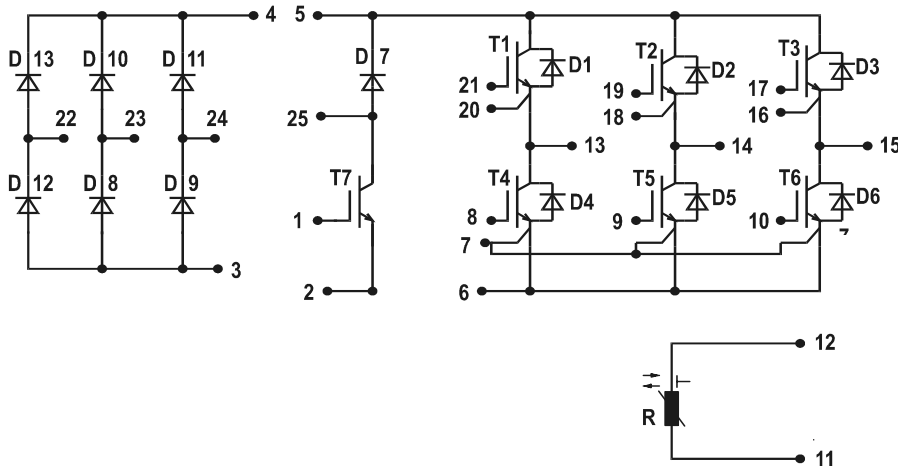


# Converter - Brake - Inverter Module (CBI1)

NPT IGBT



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600\text{ V}$	$V_{CES} = 1200\text{ V}$	$V_{CES} = 1200\text{ V}$
$I_{DAVM25} = 130\text{ A}$	$I_{C25} = 19\text{ A}$	$I_{C25} = 30\text{ A}$
$I_{FSM} = 320\text{ A}$	$V_{CE(sat)} = 2.9\text{ V}$	$V_{CE(sat)} = 3\text{ V}$

## Input Rectifier Bridge D8 - D13

Symbol	Conditions	Maximum Ratings	
$V_{RRM}$		1600	V
$I_{FAV}$	$T_C = 80^\circ\text{C}$ ; sine $180^\circ$	31	A
$I_{DAVM}$	bridge output current; $T_C = 80^\circ\text{C}$ ; rectangular; $d = 1/3$	89	A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10\text{ ms}$ ; sine $50\text{ Hz}$	320	A
$P_{tot}$	$T_C = 25^\circ\text{C}$	80	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_F$	$I_F = 30\text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.0 1.1	1.35 V V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.4	0.02 mA mA
$R_{thJC}$ $R_{thCH}$	(per diode)		0.45	1.4 K/W K/W

## Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

## Features

- High level of integration - only one power semiconductor module required for the whole drive
- Inverter with NPT IGBTs
  - low saturation voltage
  - positive temperature coefficient
  - fast switching
  - short tail current
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

**Output Inverter T1 - T6**

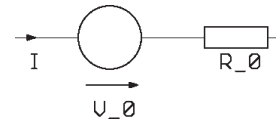
Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1200	V
$V_{GES}$	Continuous	$\pm 20$	V
$V_{GEM}$	Transient	$\pm 30$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	30	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	21	A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 82\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 60$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = 1200\text{ V}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 82\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	130	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 30\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		3.0 3.4	V V
$V_{GE(th)}$	$I_C = 0.6\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		1.5	1 mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$			200 nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600\text{ V}$ ; $I_C = 15\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 82\ \Omega$		100 80 500 70	ns ns ns ns
			2.3	mJ
			1.8	mJ
$C_{ies}$		$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$	1000	pF
$Q_{Gon}$		$V_{CE} = 600\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 17.5\text{ A}$	70	nC
$R_{thJC}$ $R_{thCH}$		(per IGBT)	0.35	0.95

**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings	
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	49	A
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	32	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 30\text{ A}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		2.0	2.9 V V
$I_{RM}$ $t_{rr}$	$I_F = 30\text{ A}$ ; $di_F/dt = -500\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600\text{ V}$ ; $V_{GE} = 0\text{ V}$		27	A
			150	ns
$R_{thJC}$ $R_{thCH}$	(per diode)	0.3	0.9	KW KW

**Equivalent Circuits for Simulation**
**Conduction**

**D8 - D13**

Rectifier Diode (typ. at  $T_J = 125^{\circ}\text{C}$ )  
 $V_0 = 0.90\text{ V}$ ;  $R_0 = 9\text{ m}\Omega$

**T1 - T6 / D1 - D6**

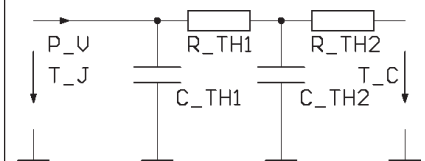
IGBT (typ. at  $V_{GE} = 15\text{ V}$ ;  $T_J = 125^{\circ}\text{C}$ )  
 $V_0 = tbd\text{ V}$ ;  $R_0 = tbd\text{ m}\Omega$

Free Wheeling Diode (typ. at  $T_J = 125^{\circ}\text{C}$ )  
 $V_0 = 1.5\text{ V}$ ;  $R_0 = 14\text{ m}\Omega$

**T7 / D7**

IGBT (typ. at  $V_{GE} = 15\text{ V}$ ;  $T_J = 125^{\circ}\text{C}$ )  
 $V_0 = 1.50\text{ V}$ ;  $R_0 = 120\text{ m}\Omega$

Free Wheeling Diode (typ. at  $T_J = 125^{\circ}\text{C}$ )  
 $V_0 = 1.46\text{ V}$ ;  $R_0 = 63\text{ m}\Omega$

**Thermal Response**

**D8 - D13**

Rectifier Diode (typ.)  
 $C_{th1} = tbd\text{ J/K}$ ;  $R_{th1} = tbd\text{ K/W}$   
 $C_{th2} = tbd\text{ J/K}$ ;  $R_{th2} = tbd\text{ K/W}$

**T1 - T6 / D1 - D6**

IGBT (typ.)  
 $C_{th1} = tbd\text{ J/K}$ ;  $R_{th1} = tbd\text{ K/W}$   
 $C_{th2} = tbd\text{ J/K}$ ;  $R_{th2} = tbd\text{ K/W}$

Free Wheeling Diode (typ.)  
 $C_{th1} = tbd\text{ J/K}$ ;  $R_{th1} = tbd\text{ K/W}$   
 $C_{th2} = tbd\text{ J/K}$ ;  $R_{th2} = tbd\text{ K/W}$

**T7 / D7**

IGBT (typ.)  
 $C_{th1} = tbd\text{ J/K}$ ;  $R_{th1} = tbd\text{ K/W}$   
 $C_{th2} = tbd\text{ J/K}$ ;  $R_{th2} = tbd\text{ K/W}$

Free Wheeling Diode (typ.)  
 $C_{th1} = tbd\text{ J/K}$ ;  $R_{th1} = tbd\text{ K/W}$   
 $C_{th2} = tbd\text{ J/K}$ ;  $R_{th2} = tbd\text{ K/W}$

**Brake Chopper T7**

Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1200	V
$V_{GES}$	Continuous	$\pm 20$	V
$V_{GEM}$	Transient	$\pm 30$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	19	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	13	A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 82\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 20$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = 720\text{ V}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 82\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	90	W

Symbol	Conditions ( $T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)	Characteristic Values		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 15\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		2.9	3.4 V
			3.5	V
$V_{GE(th)}$	$I_C = 0.4\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		0.8	0.5 mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$			100 nA
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600\text{ V}$ ; $I_C = 10\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 82\ \Omega$		45	ns
$t_r$			40	ns
$t_{d(off)}$			290	ns
$t_f$			60	ns
$E_{on}$			1.2	mJ
$E_{off}$		1.1	mJ	
$C_{ies}$	$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$		600	pF
$Q_{Gon}$	$V_{CE} = 600\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 10\text{ A}$		45	nC
$R_{thJC}$			0.45	1.37 K/W
$R_{thCH}$				K/W

**Brake Chopper D7**

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1200	V	
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	15	A	
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	10	A	
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 15\text{ A}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		2.0	3.5 V V
				0.06 mA mA
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		0.2	
$I_{RM}$	$I_F = 10\text{ A}$ ; $di_F/dt = -400\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600\text{ V}$		13	A
$t_{rr}$			110	ns
$R_{thJC}$			0.85	2.5 K/W
$R_{thCH}$				K/W

**Temperature Sensor NTC**

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$	$T = 25^{\circ}\text{C}$	4.45	4.7	5.0 k $\Omega$
$B_{25/85}$			3510	K

**Module**

Symbol	Conditions	Maximum Ratings	
$T_{VJ}$	Operating	-40...+125	$^{\circ}\text{C}$
$T_{JM}$		150	$^{\circ}\text{C}$
$T_{stg}$		-40...+125	$^{\circ}\text{C}$
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
$M_d$	Mounting torque (M4)	2.0 - 2.2	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$d_s$	Creepage distance (towards heatsink)	12.7		mm
$d_A$	Strike distance in air (towards heatsink)	12.7		mm
<b>Weight</b>		40		g

