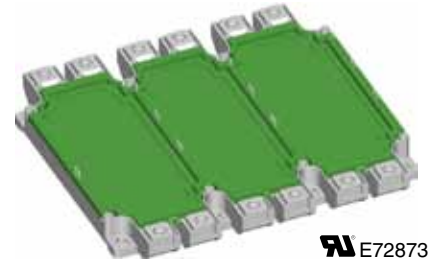
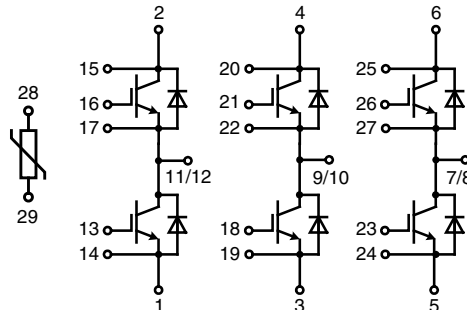


# IGBT Modules

## Sixpack

$I_{C80} = 375 \text{ A}$   
 $V_{CES} = 1200 \text{ V}$   
 $V_{CE(sat) \text{ typ.}} = 2.0 \text{ V}$



E72873

See outline drawing for pin arrangement

IGBTs			
Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^\circ\text{C to } 125^\circ\text{C}$	1200	V
$V_{GES}$		$\pm 20$	V
$I_{C25}$	$T_C = 25^\circ\text{C}$	530	A
$I_{C80}$	$T_C = 80^\circ\text{C}$	375	A
<b>RBSOA</b>	$R_G = 3.3 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 750$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ (SCSOA)	$V_{CE} = 900 \text{ V}$ ; $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 3.3 \Omega$ $T_{VJ} = 125^\circ\text{C}$ ; non-repetitive; $V_{CEmax} \leq V_{CES}$	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^\circ\text{C}$	2.1	kW

### Features

- NPT<sup>3</sup> IGBT technology
- low saturation voltage
- low switching losses
- square RBSOA, no latch up
- high short circuit capability
- positive temperature coefficient for easy paralleling
- MOS input, voltage controlled
- ultra fast free wheeling diodes
- solderable pins for PCB mounting
- package with copper base plate

### Advantages

- space savings
- reduced protection circuits
- package designed for wave soldering

### Typical Applications

- AC motor control
- AC servo and robot drives
- power supplies

Symbol	Conditions	Characteristic Values				
		$(T_{VJ} = 25^\circ\text{C}, \text{ unless otherwise specified})$				
		min.	typ.	max.		
$V_{CE(sat)}$	$I_C = 300 \text{ A}$ ; $V_{GE} = 15 \text{ V}$		2.0	2.4	V	
			2.2	2.7	V	
$V_{GE(th)}$	$I_C = 12 \text{ mA}$ ; $V_{GE} = V_{CE}$	4.5		6.5	V	
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 \text{ V}$		0.4	1	mA	
			1	12	mA	
$I_{GES}$	$V_{CE} = 0 \text{ V}$ ; $V_{GE} = \pm 20 \text{ V}$			600	nA	
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}$ ; $I_C = 300 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 3.3 \Omega$		180		ns	
$t_r$			100		ns	
$t_{d(off)}$			650		ns	
$t_f$			120		ns	
$E_{on}$				19		mJ
$E_{off}$				32		mJ
$C_{ies}$	$V_{CE} = 25 \text{ V}$ ; $V_{GE} = 0 \text{ V}$ ; $f = 1 \text{ MHz}$		22		nF	
$Q_{Gon}$	$V_{CE} = 600 \text{ V}$ ; $V_{GE} = 15 \text{ V}$ ; $I_C = 300 \text{ A}$		2.3		$\mu\text{C}$	
$R_{thJC}$				0.06	K/W	

<b>Diodes</b>			
<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>	
$I_{F80}$	$T_C = 80^\circ\text{C}$	300	A
$I_{FRM}$	$t_p = 1 \text{ ms}$	600	A
$I^2t$	$T_{VJ} = 125^\circ\text{C}; t = 10 \text{ ms}; V_R = 0 \text{ V}$	21400	A <sup>2</sup> s

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)				
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$V_F$	$I_F = 300 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^\circ\text{C}$			2.1
$I_{RM}$	$I_F = 300 \text{ A}; di_F/dt = 2700 \text{ A}/\mu\text{s}; T_{VJ} = 125^\circ\text{C}; V_R = 800 \text{ V}$		240	
$R_{thJC}$			0.11	

<b>Temperature Sensor NTC</b>				
<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$R_{25}$	$T = 25^\circ\text{C}$	4.75	5.0	5.25
$B_{25/50}$			3375	

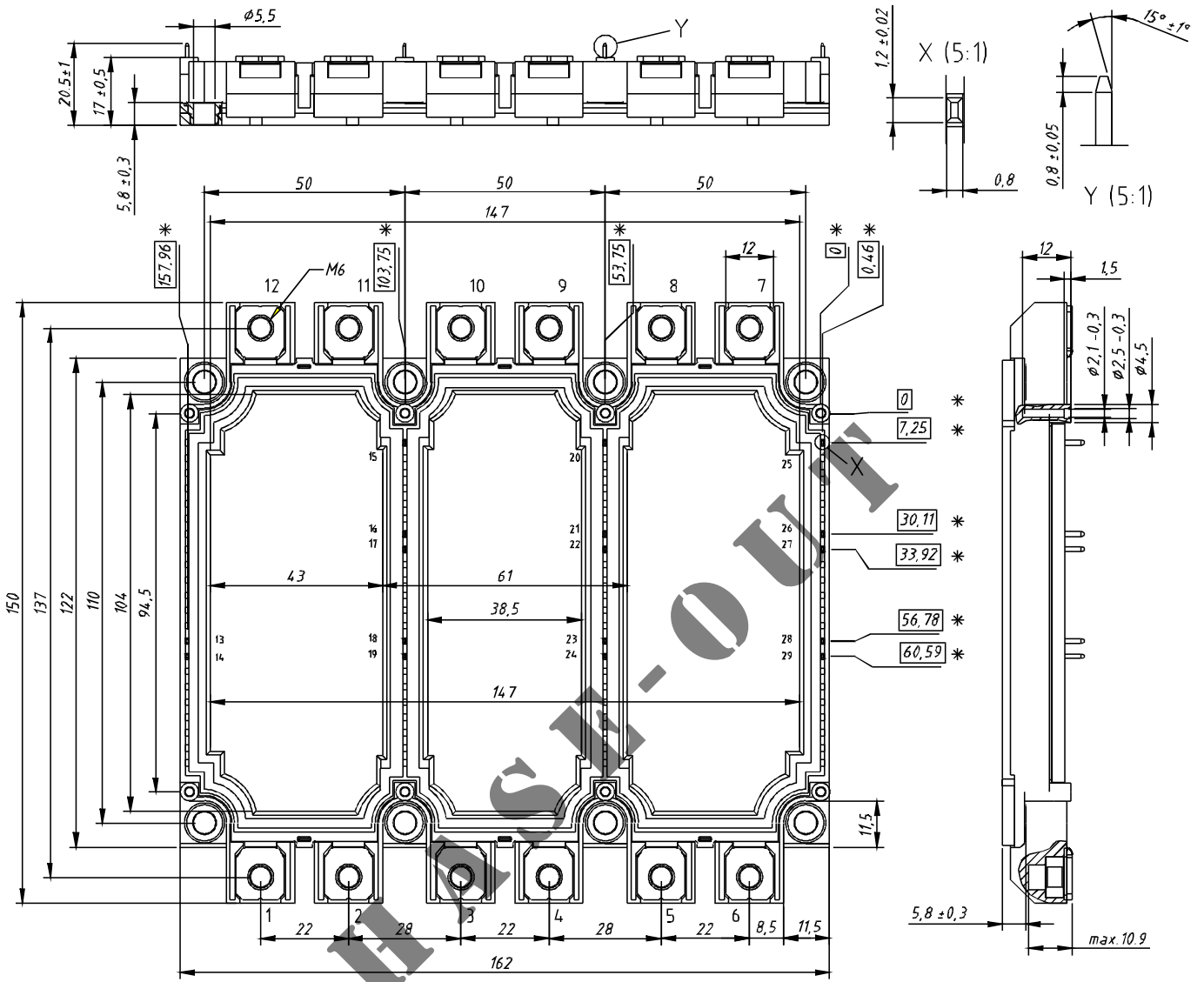
<b>Module</b>			
<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>	
$T_{VJ}$	operating	-40...+125	$^\circ\text{C}$
$T_{JM}$		+150	$^\circ\text{C}$
$T_{stg}$		-40...+125	$^\circ\text{C}$
$V_{ISO}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	3400	V~
$M_d$	Mounting torque (M5)	3 - 6	Nm
	Terminal connection torque (M6)	3 - 6	Nm

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$R_{therm-chip}^{*)}$	Resistance terminal to chip		0.55	
$d_S$	Creepage distance on surface	12.7		
$d_A$	Strike distance in air	10		
$R_{thCH}$	with heatsink compound		0.01	
<b>Weight</b>			900	

\*)  $V = V_{CEsat} + 2x R_{therm-chip} \cdot I_C$  resp.  $V = V_F + 2x R \cdot I_F$

Dimensions in mm (1 mm = 0.0394")



\* = alle Maße mit einer Toleranz von  $\pm 0.5$

= tolerance for all dimensions:

Diode		IGBT	
$R_i$	$\tau_i$	$R_i$	$\tau_i$
$2.884 \cdot 10^{-5}$	$1 \cdot 10^{-5}$	$2.344 \cdot 10^{-5}$	$1 \cdot 10^{-5}$
$1.523 \cdot 10^{-3}$	$5 \cdot 10^{-5}$	$5.97 \cdot 10^{-4}$	$5 \cdot 10^{-5}$
$7.617 \cdot 10^{-3}$	0.012	$5.97 \cdot 10^{-3}$	0.015
0.03	0.078	0.023	0.075
0.036	0.82	0.028	0.69

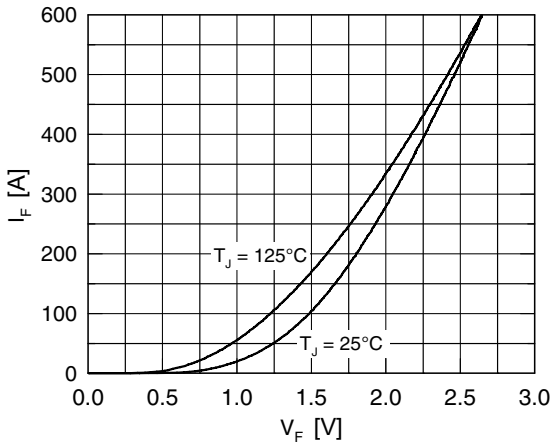


Fig. 1 Typ. forward characteristics of free wheeling diode

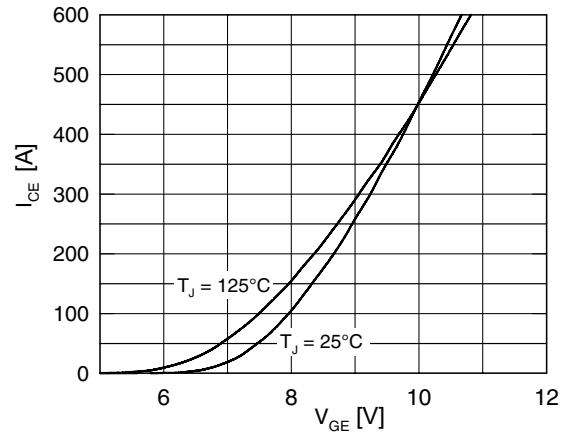


Fig. 2 Typ. transfer characteristics

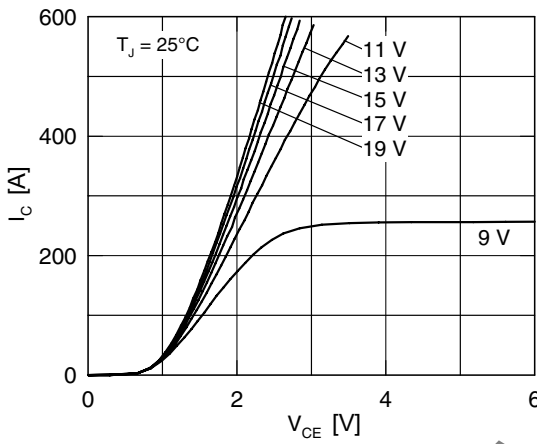


Fig. 3 Typ. output characteristics

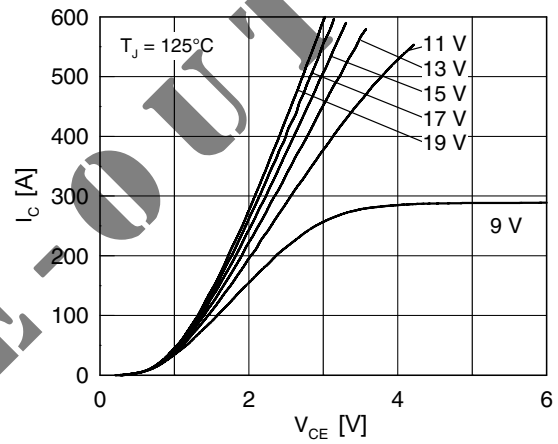


Fig. 4 Typ. output characteristics

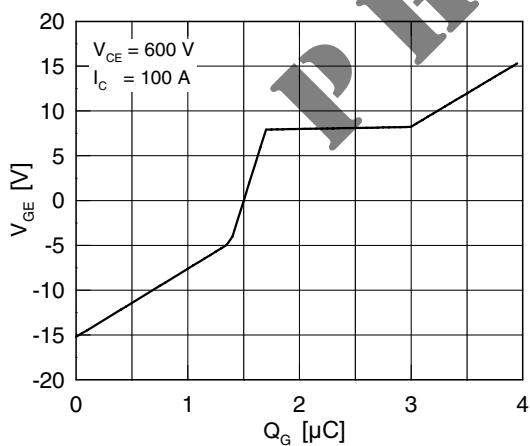


Fig. 5 Typ. turn on gate charge

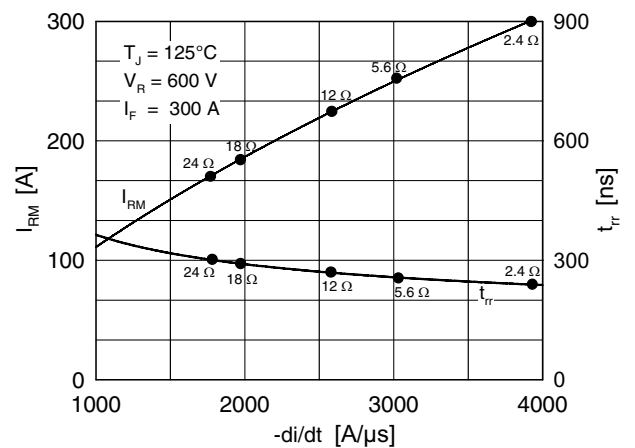


Fig. 6 Typ. turn off characteristics of free wheeling diode

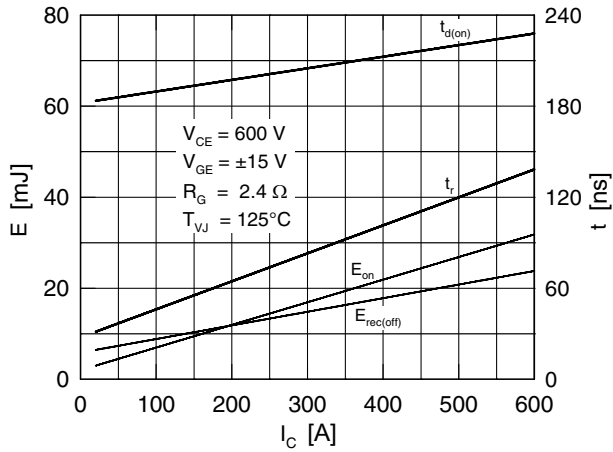


Fig. 7 Typ. turn on energy and switching times versus collector current

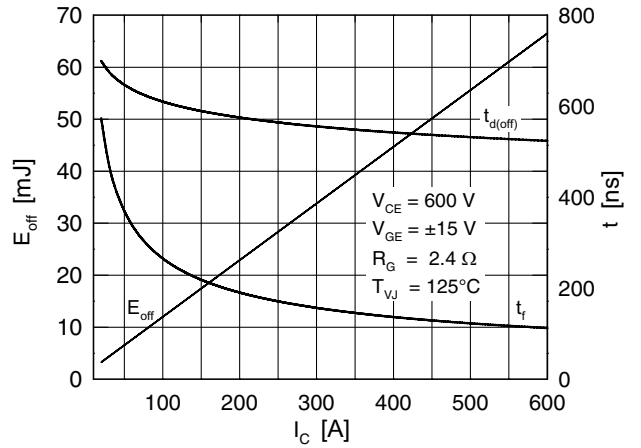


Fig. 8 Typ. turn off energy and switching times versus collector current

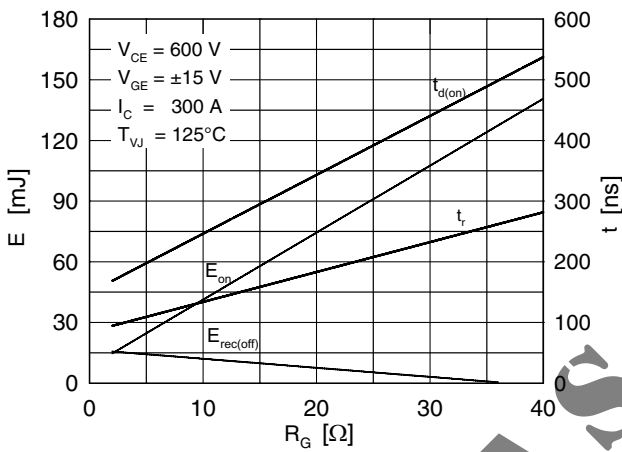


Fig. 9 Typ. turn on energy and switching times versus gate resistor

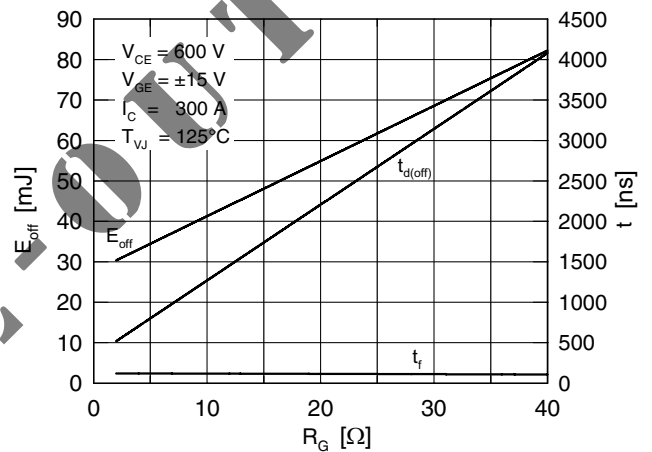


Fig. 10 Typ. turn off energy and switching times versus gate resistor

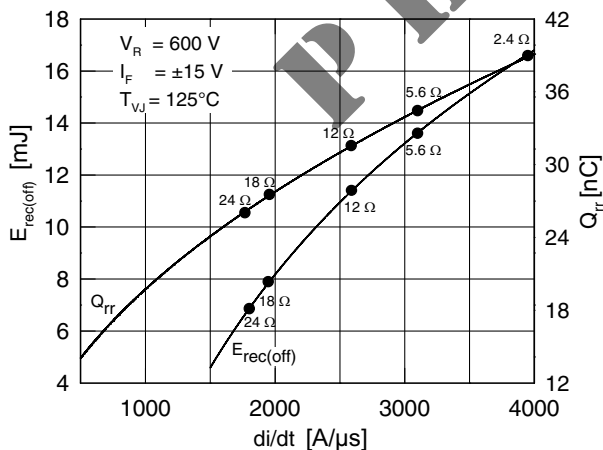


Fig. 11 Typ. turn off energy and recovered charge of free wheeling diode

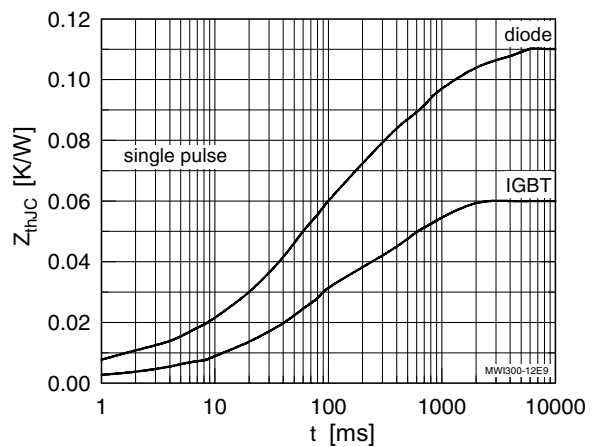


Fig. 12 Typ. transient thermal impedance