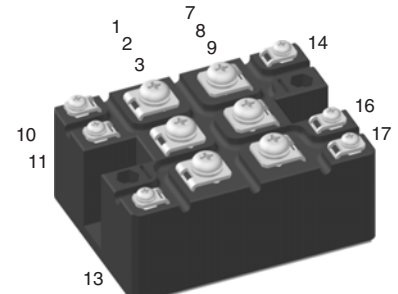
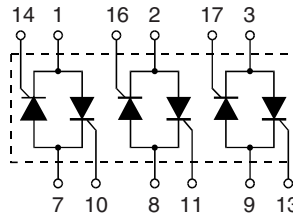


# Three Phase AC Controller Modules

$I_{RMS} = 80/95 \text{ A}$   
 $V_{RRM} = 1200/1400 \text{ V}$

Preliminary data

$V_{RSM}$	$V_{RRM}$	Type
$V_{DSM}$	$V_{DRM}$	
V	V	
1200	1200	VWO 80-12io7 VWO 95-12io7
1400	1400	VWO 80-14io7 VWO 95-14io7



Symbol	Conditions	Maximum Ratings	
		VWO 80	VWO 95
$I_{RMS}$	$T_C = 85^\circ\text{C}$ , 50 - 400 Hz (per phase)	82	96
$I_{TRMS}$	$T_{VJ} = T_{VJM}$	59	69
$I_{TAVM}$	$T_C = 85^\circ\text{C}$ ; (180° sine)	37	44
$I_{TSM}$	$T_{VJ} = 45^\circ\text{C}$ ; $t = 10 \text{ ms}$ (50 Hz), sine	1000	1150
	$V_R = 0$ ; $t = 8.3 \text{ ms}$ (60 Hz), sine	1100	1230
$I^2t$	$T_{VJ} = T_{VJM}$ ; $t = 10 \text{ ms}$ (50 Hz), sine	900	1000
	$V_R = 0$ ; $t = 8.3 \text{ ms}$ (60 Hz), sine	1000	1100
$I^2t$	$T_{VJ} = 45^\circ\text{C}$ ; $t = 10 \text{ ms}$ (50 Hz), sine	5000	6600
	$V_R = 0$ ; $t = 8.3 \text{ ms}$ (60 Hz), sine	5080	6280
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ repetitive, $I_T = 150 \text{ A}$	100	$A/\mu\text{s}$
	$f = 50 \text{ Hz}$ , $t_p = 200 \mu\text{s}$ $V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.3 \text{ A}$ non repetitive, $I_T = I_{TAVM}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	500	$A/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ ; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$ ; method 1 (linear voltage rise)	1000	$V/\mu\text{s}$
$P_{GM}$	$T_{VJ} = T_{VJM}$ ; $t_p = 30 \mu\text{s}$	10	W
	$I_T = I_{TAVM}$ ; $t_p = 300 \mu\text{s}$	5	W
$P_{GAVM}$		0.5	W
$V_{RGM}$		10	V
$T_{VJ}$		-40...+125	$^\circ\text{C}$
$T_{VJM}$		125	$^\circ\text{C}$
$T_{stg}$		-40...+125	$^\circ\text{C}$
$V_{ISOL}$	50/60 Hz, RMS; $t = 1 \text{ min}$	2500	V~
	$I_{ISOL} \leq 1 \text{ mA}$ ; $t = 1 \text{ s}$	3000	V~
$M_d$	Mounting torque (M5)	5/44±15 %	Nm/lb.in.
	Terminal connection torque (M3; M5)	1.5/13±15 %	Nm/lb.in.
Weight	typ.	250	g

## Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Package with metal base plate
- Isolation voltage 3000 V~
- Planar passivated chips
- UL applied

## Applications

- Switching and control of three phase AC circuits
- Softstart AC motor controller
- Solid state switches
- Light and temperature control

## Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density

Data according to IEC 60747 refer to a single thyristor/diode unless otherwise stated.

Symbol	Conditions	Characteristic Values		
			VWO 80	VWO 95
$I_D, I_R$	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	$\leq$	5	5 mA
$V_T$	$I_T = 150 \text{ A}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.65	1.57 V
$V_{T0}$	For power-loss calculations only		0.85	0.85 V
$r_T$			5.2	4.8 m $\Omega$
$V_{GT}$	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.0	1.0 V
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	1.6	1.6 V
$I_{GT}$	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	100	100 mA
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	150	150 mA
$V_{GD}$	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	$\leq$	0.2	0.2 V
$I_{GD}$		$\leq$	5	5 mA
$I_L$	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$	$\leq$	200	200 mA
$I_H$	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	$\leq$	150	150 mA
$t_{gd}$	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$	$\leq$	2	2 $\mu\text{s}$
$t_q$	$T_{VJ} = T_{VJM}; I_T = 20 \text{ A}, t_p = 200 \mu\text{s};$ $di/dt = -10 \text{ A}/\mu\text{s}$ typ. $V_R = 100 \text{ V}; dv/dt = 15 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$		150	150 $\mu\text{s}$
$R_{thJC}$	per thyristor; sine 180°el		0.81	0.66 K/W
	per module		0.135	0.11 K/W
$R_{thJK}$	per thyristor; sine 180°el		1.0	0.93 K/W
	per module		0.167	0.155 K/W
$d_s$	Creeping distance on surface		8.0	mm
$d_A$	Creepage distance in air		4.5	mm
$a$	Max. allowable acceleration		50	m/s <sup>2</sup>

